| CV	Description	Area	Value*
1	**Locomotive address**	DCC: 1 - 127 Mot: 1 - 80	3
2	**Minimum speed** (the speed from 0 until the locomotive is running at speed step 1)	0 - 255	0
3	**Acceleration delay**	0 - 255	50
4	**Braking delay**	0 - 255	30
5	**Maximum speed** (must be greater than CV 2)	0 - 255	200
6	**Average speed** (must be greater than CV 2 and less than CV 5)	0 - 255	100
7	**Firmware version** (The processor can be updated)	-	differently
8	**Manufacturer's ID** Decoderreset CV8 = 8	different	162
12	**Decoder operating mode** **Value** Bit 0=1 DC (analog operation; direct current) on *1 Bit 2=1 DCC data format on *4 Bit 4=1 AC (analog 3-rail operation; alternating current) on *16 Bit 5=1 Motorola® data format on *32 Bit 6=1 mfx® data format on *64	0 - 117	117
17 18	**Long locomotive address** 17 = high Byte 18 = low Byte	1 - 10239 192 - 231 0 - 255	1000 195 232
27	**Brake signal settings (automatic stop)** **Value** Bit 0 = 1 -> ABC (Automatic Brake Control) right rail positive 1 Bit 1 = 1 -> ABC left rail positive 2 Bit 4 = 1 -> DC; opposite direction of travel 16 Bit 5 = 1 -> DC; same direction of travel 32	0 - 51	0
29	**DCC standard configuration** **Value** Bit 0=0 Normal direction of travel *0 Bit 0=1 Opposite direction of travel 1 Bit 1=0 14 speed steps 0 Bit 1=1 28 speed steps *2 Bit 2=0 Digital mode only 0 Bit 2=1 Automatic analog/digital recognition *4 Bit 3=0 RailCom® turned off 0 Bit 3=1 RailCom® turned on *8 Bit 4=0 Speed steps over CV 2, 5, and 6 *0 Bit 4=1 Use the characteristic curve from CV 67 - 94 16 Bit 5=0 Short address (CV1) *0 Bit 5=1 Long address (CV 17/18) 32	0 - 63	14
30	**Error codes for the motor, thermal overload, and function outputs:** 1 = motor error, 2 = thermal overload error, 4 = function output error	0 - 7	0

* set ex works

Function assignments

F0	Licgt	F8	Automatic Spring Brake	F16	Engine Room Door
F1	Sound	F9	Compressor	F17	Fan
F2	High Tone Horn	F10	Cab Door	F18	Conducter's Whistle
F3	Station announcement 1	F11	Cab Window	F19	Sanding
F4	Station announcement 2	F12	Pantograph	F20	Air Valve Release
F5	Volume control	F13	Dead Man's Peda	F21	Curve Squeal
F6	Tunnel mode	F14	Train Brakes	F22	Clickety-Clack
F7	Switching Gear	F15	Coupling	F23	-

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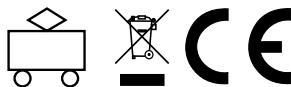
#56613 PIKO SmartDecoder XP 5.1 Sound NEM652 for Electric locomotives BR 185.2 multiprotocol, mfx® capability included

PIKO
MODELLBAHNEN & GEBÄUDEMODELLE

NOTE: Detailed information on the PIKO SmartDecoder XP 5.1 Sound is available as a PDF file on our Webshop on the page of the respective item number. The file contains a full description of all functions and operating possibilities for the new SmartDecoder XP 5.1 Sound.

Description
The state-of-the-art PIKO SmartDecoder XP 5.1 Sound inside this PIKO locomotive is a compact yet powerful multi-protocol NEM652 sound decoder. It features high fidelity, 12 bit 8-channel sound with 2.5 watts of output that ensures distortion-free sound at all levels. It complies with the current RCN standards in all areas. The decoder can be used on DCC, mfx®, and Motorola® digital systems as well as traditional DC or AC analog layouts. It automatically senses what operating mode is used on your layout and is RailCom®/RailCom Plus® compatible. The PIKO SmartDecoder XP 5.1 Sound features several programmable braking distance functions in addition to numerous other programmable functions.

The PIKO SmartDecoder XP5.1 Sound is load-regulated and features auto-adaptive motor control that works with of a fundamentally newly developed traditional DC motors for a silky smooth ride as well as 1.2 Amp coreless motors. The decoder will also tolerate a temporary current draw up to 2 Amps. The sound decoder masters ABC braking, ABC shuttle automatic, as well as ABC slow speed.The motor speed table can be set using the minimum, median, and maximum motor speed (simple curve), or by the user-programable 28-speed step extended curve. The decoder features two directional lighting outputsas well as via an additional special function output which can be that can be activated using function keys up to F68 (DCC). The switching (shunting) gear, with extended slow speed range, the three possible starting and braking delays, as well as the many vehicle sounds are also switchable via function keys. The sound part can control specified function outputs as well as the motor output of the decoder. The PIKO SmartDecoder XP 5.1 is supported by the further developed power management in case of short-term voltage loss..

Installing the PIKO SmartDecoder XP 5.1 Sound
Remove the jumper plug from your model's NEM 652 interface. At the same place insert the 8-pin plug of the decoder carefully into the interface socket. Please note the coding of PIN 1 note. If the plug is turned 180°, the locomotive will run in the wrong direction and the light will not work. Check for crossed wires and short circuits before and after reinstalling the shell. Place the model on your programming track with programming mode activated on your DCC system. During programming or when reading the model's DCC address, a small amount of current will flow through the model, which does not affect the decoder; even in the event of a short circuit.

Special function A1
The special function output A1 of the PIKO SmartDecoder XP 5.1 can only be used if the desired consumer is already connected to the NEM 652 interface in the vehicle, or if there are solder pads on the main board.

> **A short circuit in the motor, lighting, pick-up wiper, or wheelsets can destroy the decoder as well as the electronics of the model!**

First-time use of the decoder (state of delivery)
Enter address 3 on your digital control system. Depending on the data format used to address the sound decoder, the locomotive runs in DCC mode with 28 speed steps or in Motorola® mode. When using a RailCom Plus®-enabled system or with an mfx®-capable system, the decoder is detected automatically and can be operated immediately. If the decoder is used on a conventional analog layout, it can be controlled with a DC or AC power pack. The decoder will automatically detect the layout's operating mode.

NOTE: In DC mode, your vehicle will not start until the voltage is higher (speed control turned up further) than you may have been used to when operating with analog vehicles.

Function outputs in analog mode
It is possible to program the decoder so that function keys F0 - F12 (as they are assigned in the function mapping) can also be activated in analog mode. To do this, CVs 13 & 14 must first be programmed with a central control unit. The corresponding values can be found in the CV table of the detailed operating instructions.
The light function F0 and the motor sound F1 are switched on ex works.

Motorola®
The decoder utilizes 4 Motorola® addresses to access functions F1 - F 16, when using a Motorola—based command station. The three sequence addresses for the functions F5 - F16 are ascending to the decoder address and can be activated in CV61 as required by the values 1 (F5 - F8), 2 (F5 - F12), or 3 (F5 - F16).

Configuration of CVs
CVs 12 and 29 control the operating mode and configuration CVs, respectively. As a rule, an indexed CV contains various basic settings of a decoder, such as reversing the direction of travel. CV calculation examples can be found in the detailed operating instructions.

RailCom®, RailCom Plus®
In the sound decoder, CV29 (RailCom®) can be turned on or off via bit 3. The decoder is automatically recognized by RailCom Plus® - equipped command stations (like PIKO SmartControl) if the RailCom Plus® option is activated in CV 28. The decoder name, locomotive symbol, and special function symbols will appear automatically on your control device's screen. With RailCom Plus® technology, no locomotive data has to be stored in the DCC central control unit and no locomotive addresses have to be programmed into the decoder.

mfx®
The PIKO SmartDecoder XP 5.1 Sound also masters the mfx® data format. The decoder is automatically recognized on mfx®-equipped command stations. The decoder name and its maximum of 16 special function symbols automatically (license required).
This mfx® technology means that no locomotive data has to be stored in the command station and no locomotive addresses have to be programmed into the sound decoder.

Braking
The sound decoder understands the following braking methods:
Märklin® braking section (brakes with analog DC voltage)
DCC braking function
ABC (Automatic Brake Control) braking section
The decoder's adjustable braking distance can bring the train to a stop within a centimeter of a signal. More information on "braking behavior" can be found in the detailed operating instructions for PIKO SmartDecoder XP 5.1 Sound.

Shunting speed (RG)
The desired function key F0 - F68, via which the shunting speed (half speed) can be switched on, is entered in CV157.

Starting and braking delays (ABV)
The desired function key F0 - F68, which can be used to switch off the ABV, is entered in CV156. The values of the starting and braking delays can be changed in CVs 3 and 4.

Function outputs
A comprehensive description of all options related to the function outputs can be found in the detailed operating instructions.

Simple and extended function mapping
In the simple function mapping according to RCN-225 (CVs 33 - 46) the switching tasks such as lighting and special function output can be freely assigned to the function keys F0 to F12 of the digital command station. The switchable starting and braking delay and the shunting gear can be assigned to any function key up to F68 in CVs 156 and 157 can be assigned to any function keys up to F68. More information can be found in the detailed operating instructions.

Smoke generator control
A smoke generator can be connected to output A1, which can be controlled by the decoder either load- or speed-dependent.
speed-dependent by the decoder. The assignment to the function keys is done exclusively via the extended function mapping extended function mapping.

Extended function mapping
Due to its complex nature, extended **function mapping** cannot easily be set by programming individual CVs. To work with extended **function mapping**, you will need the PIKO SmartProgrammer device (#56415) and, if desired, the PIKO SmartTester (#56416). Detailed information on extended function mapping is available in the instruction manual.

Servo control
The decoder enables the control of a servo motor via function output A1. The assignment to the function keys is done exclusively via the extended function mapping.

The use of a servo with the decoder requires electronics expertise.

Further information can be found in the detailed operating instructions.

ATTENTION: Soldering on the decoder should only be carried out by experienced specialists with the appropriate tools. Decoders damaged by improper handling will not be covered by the warranty.

Sound settings
To change the overall sound volume of the SmartDecoder XP 5.1 Sound, first program CV31 to a value of 2 and CV32 to a value of 0.
This will take you to the programming area for setting the total volume. You can now set this as you wish in CV257 in the value range 0 - 255.

NOTE: In order to play a PIKO sound on the sound decoder, the test and programming device requires PIKO SmartProgrammer (#56415) and (optional) the PIKO SmartTester (#56416).
All further information about the sound section of the PIKO SmartDecoder XP 5.1 Sound as well as the available For setting options, please refer to the detailed operating instructions.

Factory reset
To restore the sound decoder to its factory settings, program CV8 to a value of 8.

Programming
Configuration variables (CVs) form the basis of all the decoder's settings. This decoder can be used with the PIKO SmartControl*light* DCC system, the PIKO SmartControl DCC system, or any other Motorola-based system. For more information on programming options, please refer to the instruction manual.

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Motorola® is a registered trademark of Motorola Inc. Tempe, (Phoenix) Arizona / USA
RailCom® and RailComPlus® are registered trademarks of Lenz Elektronik GmbH, 35398 Gießen

NOTE: This product is not a toy and is not suitable for children under the age of 14. Any liability for damage of any kind caused by improper use or failure to observe these instructions is excluded.

Warranty Statement
Each decoder module is fully tested before shipment. Nevertheless, should a malfunction occur within the 2-year warranty period, we will repair the module free of charge on presentation of the proof of purchase. This warranty is voided if the unit has been damaged by improper use. Please note that, according to the German Electromagnetic Compatibility Law (EMV-Gesetz), the decoder module may only be used inside models bearing the CE mark.